

A Review on Curbing of Power System Oscillation using STATCOM

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Abstract: A control methodology that boosts dynamic and responsive power infusion at different association focuses from the STATCOM will be determine amid the improved model. The proposed procedure is powerful in expanding the damping from the framework in the wavelengths of awesome intrigue, and in the circumstance of framework parameter vulnerabilities furthermore at different association focuses from the compensator. A set up of a STATCOM with vitality stockpiling has as of now been situated in the U.K. for power stream administration and current control. This paper handles the style of a versatile power wavering damping (POD) controller for any static synchronous compensator(STATCOM)furnished with vitality stockpiling. This is accomplished using a flag estimation strategy with various altered recursive slightest square (RLS) equation, which empowers a brisk, meticulous, and versatile estimation from the low-recurrence electro mechanical motions from in your general vicinity measured signs amid power framework aggravations. Within the particular circumstance of shunt associated Details controllers STATCOM and static var-compensator (SVC). In the first place, the exploration into the effect of dynamic and responsive power infusion into the power framework will be transported out using a basic two-machine framework demonstrate. Little flag inquire about into the dynamic execution from the proposed control procedure will be transported out. The intensity of the recommended control way to deal with give control swaying damping paying little mind to the bond explanation behind the gadget and also in the presence of framework parameter instabilities will be checked through recreation and trial comes about.

Keywords: Energy Storage, Low-Frequency Oscillation, Power Oscillation Damping (POD), Recursive Least Square (RLS), Static Synchronous Compensator (STATCOM).

I. INTRODUCTION

Although typically employed for reactive power injection only, by equipping the STATCOM by having an energy storage connected to the electricity-link from the ripper tools, a far more flexible charge of the transmission system could be accomplished [4]. STATIC synchronous compensator (STATCOM) is really a key device for reinforcement from the stability within a nac power system. This product continues to be applied both at distribution level to mitigate power quality phenomena and also at

transmission level for voltage control and power oscillation damping (POD) [1].Within the specific situation of shunt connected Details controllers STATCOM and static vary compensator (SVC), first swing stability and POD could be accomplished by modulating the current at the reason for common coupling (PCC) using reactive power injection. A set up of a STATCOM with energy storage has already been based in the U.K. for power flow management and current control [2]. The introduction of wind energy along with other distributed generation will pave the way in which for additional energy storage in to the power system and auxiliary stability enhancement function can be done from the energy sources Low-frequency electromechanical oscillations (typically in the selection of .2 to two Hz) are typical within the power system and really are a reason to be concerned regarding secure system operation, particularly in an inadequate transmission system.

In this regard, Details controllers, in shunt and series configuration, happen to be broadly accustomed to enhance stability from the power system[3]. However, one disadvantage to the shunt configuration for this type of programs would be that the PCC current should be regulated within specific limits and this reduces the quantity of damping that can be supplied by the compensator. Furthermore, the quantity of injected reactive power required to modulate the PCC current depends on rapid circuit impedance from the grid seen in the connection point. Injection of active power, however, affects the PCC-current angle without different the current magnitude considerably.

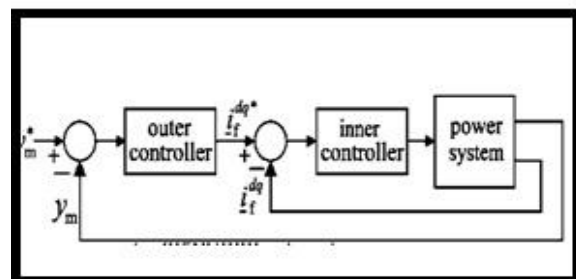


Fig.1. Block diagram of the STATCOM.

The charge of STATCOM with energy storage (named hereafter as E-STATCOM) for power system stability enhancement has been talked about within the literature When active power injection is used for POD, the position of

the E-STATCOM has a significant impact on its dynamic performance. Furthermore, the normal control strategy from the device for POD obtainable in the literature is similar towards the one employed for power system stabilizer (PSS) where a number of wash-out and lead-lag filter links are utilized to generate the control input signals. This type of control strategy is effective limited to the operating point where the style of the filter links is enhanced, and it is speed of fact is limited by the frequency from the electromechanical oscillations. Within this paper, a control technique for the E-STATCOM when used for POD is going to be investigated. Because of the selected local signal amounts measured within the system, the control strategy optimizes the injection of active and reactive capacity to provide uniform damping at various locations within the power system. It will be proven the implemented control formula is robust against system parameter uncertainties. With this, an altered recursive least square (RLS)-based estimation algorithm will be employed to extract the needed control signals from in your area measured signals. Finally, the success. From the suggested control strategy is going to be validated via simulation and experimental verification.

II. SYSTEM MODELING FOR CONTROLLER DESIGN

A simplified power system model, like the one depicted in Fig1, can be used to review the outcome from the E-STATCOM on the power system dynamics. The investigated system approximates an aggregate type of a 2-area power system, where each area is symbolized with a synchronous generator. The charge of the E-STATCOM includes an outer control loop as well as an inner current control loop in this paper, the outer control loop is assumed to become a POD controller, Because of this, we think that the injected active and reactive forces within the steady condition are zero. When designing a cascaded controller, the rate of outer control loop is typically selected to become much reduced compared to inner one to guarantee stability. This means that the present controller can be considered infinitely fast when creating the parameters of the outer controller loop. Therefore, the E-STATCOM can be modeled like a controlled ideal current source, The amount of power oscillation damping supplied by the converter is dependent about how much the active output from the machines is modulated through the injected current,

III. POD CONTROLLER DESIGN

The derivation from the POD controller from in your area measured signals is going to be produced in this.

A. Derivation of Control Input Signals

Thinking about the simplified two-machine system in Fig1, the active output from each generator should alternation in Proportion towards the alternation in its speed to supply damping.

B. Estimation of Control Input Signals

As described within the Introduction, effective power oscillation damping for a number of power system operating points Andes-STATCOM locations require fast, accurate,

and adaptive estimation of the critical power oscillation frequency component. This really is accomplished through an estimation method according to a modified RLS formula. For reasons described within the previous subsection, the derivative from the PCC-current phase and the transmitted power ought to be believed for manipulating the active and reactive power injection, correspondingly as shown in Fig.2. The goal of the algorithm thus remains to estimate the signal components that consist of just the reduced-frequency electromechanical oscillation.

- Modification within the Conventional RLS Formula:
- Modification for Multiple Oscillation Modes:

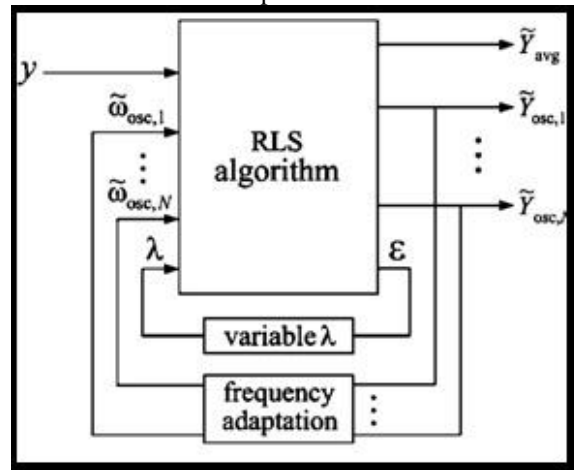


Fig.2. Framework of the modified RLS.

IV. STABILITY ANALYSIS OF SYSTEM MODEL

The mathematical type of the system is developed in this to research the performance from the POD controller using active and reactive power injection.

V. SIMULATION RESULTS

Simulation results of this paper is as shown in bellow Figs.3 to 5.

A. IPOD Controller With E-Statcom

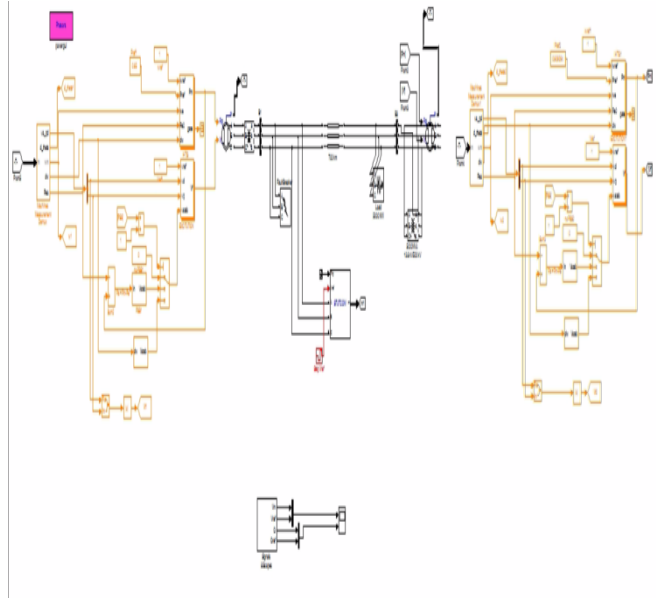


Fig.3. POD controller deign.

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B.E-Statcom for the Reactive and Active Power Injection

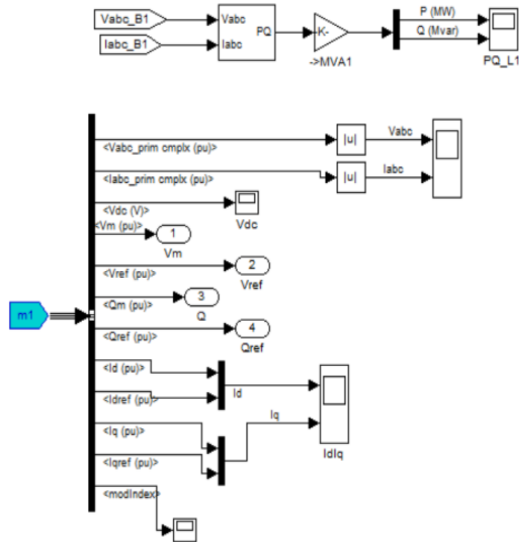
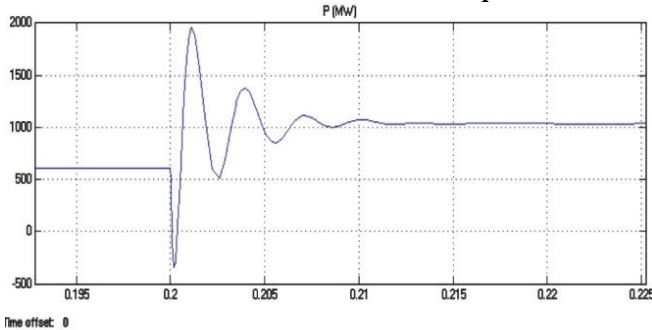
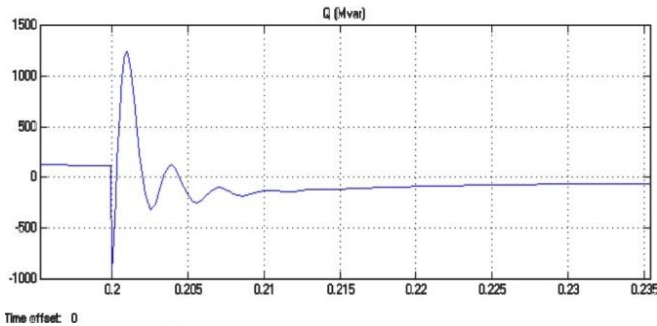


Fig.4. POD controller design with E-STATCOM for the reactive and active power injection.

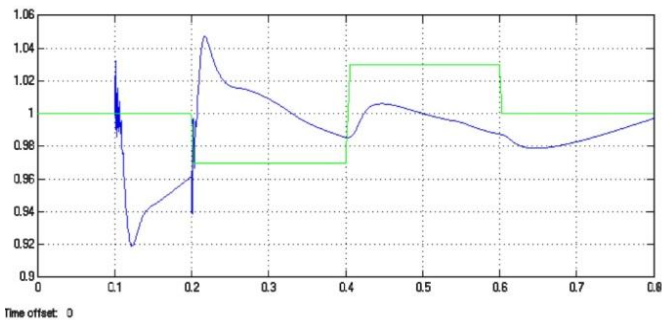
C. Measured Generator Power Output For Three-Phase Fault With E-Statcom With Different Frequencies



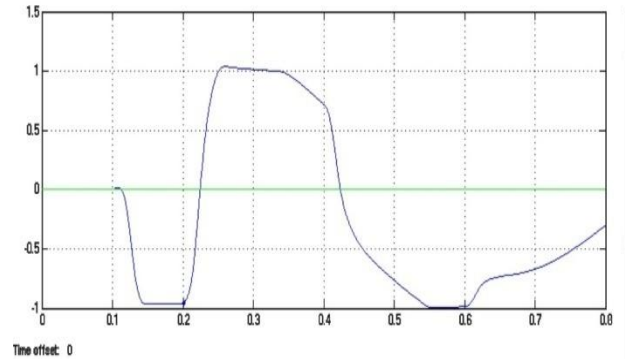
(a)



(b)



(c)



(d)

Fig.5. POD controller design with E-STATCOM output for the different frequencies modes.

VI. CONCLUSION

The estimator allows a fast, selective and adaptive estimation of signal components at the power oscillation frequency. The dynamic performance of the POD controller to supply effective damping at various connection points from the E-STATCOM continues to be validated through simulation in addition to experimental verification. The robustness of the control formula against system parameter changes has been proven through experimental tests. An adaptive POD controller by E-STATCOM has been developed within this paper. The charge of STATCOM with energy storage (named hereafter as E-STATCOM) for power system stability enhancement has been talked about within the literature. When active power injection is used for POD, the position of the E-STATCOM has a significant impact on its dynamic performance. With this, an altered RLS formula has been employed for estimation from the low-frequency electromechanical oscillation aspects of in your area measured signals during power system disturbances. In addition, while using frequency variation in the E-STATCOM connection point because the input signal for that active power modulation, it has been proven that active power injection is minimized at points in the ability system where its effect on POD is minimal. This leads to an ideal utilization of the available power source.

VI. REFERENCES

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